

## **Advanced Training Systems**

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## M-145 OPERATIONS GUIDE



## Set Up:

Unpack the M-145 Robotic Platform, Save the packing material in case the unit must be sent in for repair. In the carton are several smaller boxes. Inside of one box is the post; inside of a second box are the transmitter and other accessories.



Note the location of the power switch on the side. The antenna is mounted on the top deck.

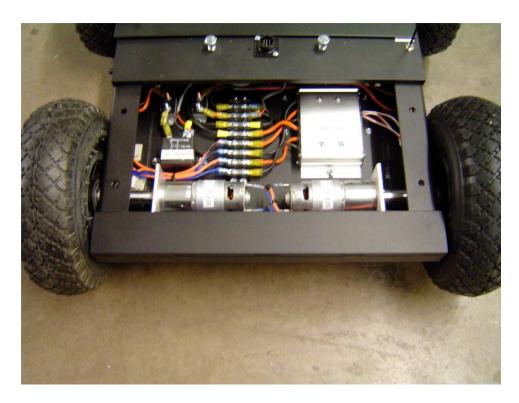
To mount the post ensure the power switch is in the off position, mate the circular on the top of the platform with the pigtail inside post. Mate the connector and lock the collar on the circular connector. After the connector is mated, bolt the post in place with the provided hardware, the switches are placed to the rear (battery end with blank plate). The base platform will not operate without the post mounted. It is possible to create a jumper to test the base unit. Contact the factory for this option.



To remove a cover simply pull on each of the 4 plastic rivets until they click; about ¼" is all they move. The center Pin of the Rivet will stay in the fastener. When all 4 rivets are loose, grab 2 rivets on opposite sides of the cover and pull up.

To reinstall set the cover into place, align the 4 rivets and push each of the 4 center lock pins until the snap action is felt. No tools are required.

The cover with the M-145 sticker is the front of the unit. The motor controller and radio receiver are located under this cover. Two circuit breakers as well as a terminal block and power disconnect relay are under this cover also.



The bare cover (no logo) is the rear of the unit (may have loop hanldes) and is where the 2 batteries are located. The unit uses two 12V 7.5Ah Sealed Lead Acid Batteries for its power source wired in series to create 24V. This is a 24V system using two 12V batteries. Both Batteries are required to operate the system. These batteries use the T2 style of terminal, if replacing the batteries ensure that T2 terminals are used. To connect the batteries attach both sets of Red and Black cables to the proper terminals on the batteries, ensuring the connections are secure. If it has loop handles, the cover is fastened using high strength Vlecro©, so just pull straight up, hard, and it should pop off.



Caution: When charging you MUST remove both sets of battery cables from both batteries before connecting the charger; Failure to do so will cause damage to the charger, wiring and robotic platform.

To charge the batteries, remove both sets of red and black cables from both batteries. Connect the alligator clips on the charger to matching color on one battery at a time. Charge the batteries one at a time to avoid damage to the system or batteries by using heavy-duty jumpers it is possible to charge both batteries from one charger but we do not suggest this method of charging.

You can purchase a second charger to charge the second battery at the same time.

To change the batteries, loosen the wing nut, and slide the battery clamp aside. Slide the battery out while tilting up. Insert New Battery, install clamp and tighten wing nut. At this point connect both sets of leads and reinstall cover.

Do not allow the batteries to become deeply discharged. Running the batteries too low can cause decreased battery life or even battery failure. If the batteries drop to 9V or below they should be charged immediately.

It is good practice to turn the transmitter on before the M-145 Robotic Platform.

To operate the unit, turn the Transmitter ON and then flip the Power Switch UP. The unit is now ready to drive.

Each radio unit has a unique ID code that links the transmitter to the receiver. The system operates on 2.4GHz spread Spectrum Frequency Hopping scheme. The radios are off the shelf consumer units and must be replaced as a pair. If multiple units are ordered at the same time they will be labeled with a "Unit" number on the Base near the antenna and on the transmitter. Transmitters are interchangeable between units.

The M-145 moves forward and Backwards by using the trigger on the hand held transmitter. The steering wheel on the transmitter controls left and Right turning. The M-145 operates in a skid steer type of operation. If no forward or reverse command is given the unit will still spin and turn.

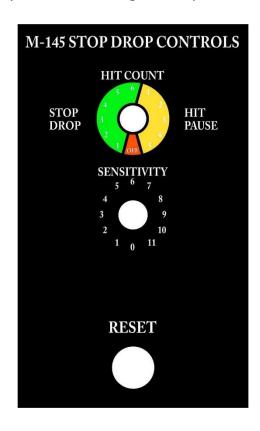
Upon power up the hit detection system is disabled. To enable simply press the Red Reset Button located on the back of the post.

The unit is shipped from the factory with the hit detection board disabled. There are two modes of operation. The first mode is Hit-Stop the second is Hit-Pause. In hit stop mode the unit detects and counts, when the correct count is reached the unit will stop, drop the mannequin and wait for the dummy to be replaced and reset button pressed. In hit pause mode the

impacts are counted and the when the count is reached the platform will pause for 5 seconds and resume motion as commanded after time expires.



There are two Knobs on the post to control the hit settings. The top knob sets the count and mode. The bottom knob sets the sensitivity. Any time a change is to be made the power should be turned off. Upon power up, the reset button must be pressed to energize the post.



The top knob controls 3 modes. When set to 0 the post is disabled. Pressing the reset button with the knob set to 0 will cause the latch to disengage. Positions 1-6 control Hit-Stop/Drop mode with the number controlling the number impacts to activate the latch. Positions 7-11 on the switch control the Hit-pause mode with 1-5 hits to activate.

The bottom knob controls sensitivity. 0 is the most sensitive. The larger the number the bigger the impact required to trip the sensor. The normal range for operation is 4 through 8 depending on the caliber used. A knob setting of 4 works well with 5.56mm rounds. A setting of 6 will work well with 40 S&W.

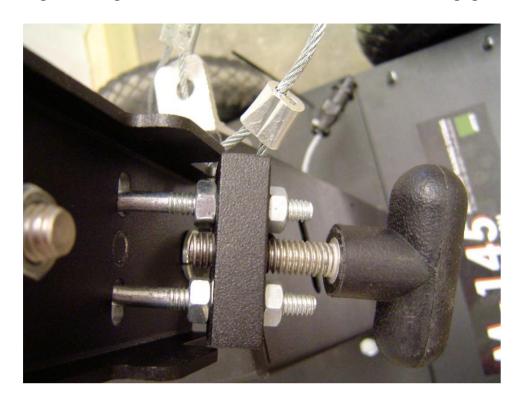
Setting the sensitivity is a balance of not detecting bumps and vibrations from the M-145 platform in motion but detecting bullet impacts to the torso. To experiment with the sensitivity set the Hit-Pause to 1, press the reset button and drive the unit around. If the platform stops and pauses it is detecting false triggers, increase the setting on the bottom knob. Once no false hits are detected test with live fire to ensure the unit operates correctly. The power should be turned off and the reset button must be pressed any time a change is made to the knob settings.

In Stop/Drop mode the bracket is released from the latch when the correct number of impacts has been detected.



The bracket is tethered to the post. Removing the tether can cause the bracket to fall straight down crushing the covers. Do not remove the tether.

To replace the bracket after it has fallen, loosen the hand knob 1 to 2 turns. This will give enough slack in the U-Bolt to allow the latch to engage.



After loosening the hand knob, grab the knob and bar attaching the U-Bolt in the palm of your hand pressing the U-Bolt as far through the bracket as possible. Guide the 2 Pins into the matching holes in the post and the U-Bolt into the slot. You will feel the Latch engage. If the latch does not engage, loosen the hand Knob further and retry.



Once the bracket is latched in place, tighten the bracket to the pole by turning the hand knob. If the bracket is too loose the mannequin will flop all over. There is no need to over-tighten the knob, it is only required to snug the bracket and take up most of the slop.

Once the bracket is in place the 2" PVC pole can placed over the bracket with the mannequin on top of the Pole.



The mannequin is shipped from the factory ready to be assembled and prewired. If replacing the sensor it is important to place the duct tape over the sensor as shown below. When assembling the mannequin ensure the legs are mounted as shown above and the wires are routed as shown.

The pole has a large screw in the top of the post, remove this screw before inserting the pole into the body. There are two washers on this bolt. It is recommended that the star washer be placed between the top of the pole body, inside the pocket. The large flat washer goes directly under the bolt head.



The bottom end of the pole is keyed to keep the mannequin aligned. The back of the pole has an indication line, this line marks key slot for the pole. This indicator marks the back of the pole. The bracket has 4 tabs, one of which is ½" taller than the rest, this is the key and is the rear of the unit. When installing the post into the mannequin, align the mark before tightening the screw.



The M-145 is a Cost Effective Light Duty Robotic Platform designed to be quick and agile. The unit has a limited carrying capacity of 35#. A mannequin weights approximately 9 pounds. Overloading the M-145 will make it harder for the unit to turn and accelerate, decreasing performance. The more weight placed on the M-145 the shorter battery life will become.

Overloading the M-145 will cause premature motor wear. Motors are field replaceable.

## Maintenance

If the wires are damaged during use connectors have been provided. There are 3 wires inside the cable; Red, Black, and a bare wire. All 3 wires are required for the unit to operate correctly. When making repairs make sure all wires are connected. To use the repair connectors, simply slip the loose ends into the connector and crimp shut with a pair of pliers. No stripping is required. These same styles of connectors are used to connect the hit sensor.



To replace a wheel simply remove the one bolt in the end of the axle shaft, remove the keyed wheel retainer, slip the tire and wheel off the axle. Next replace with a new wheel assembly and reinstall the Key. Install the washer and Bolt and tighten. If when reinstalling the wheel the keyed retainer does not mate up with the webs in the wheel, flip the key backwards and use it as a wrench to rotate the wheel on the shaft to the correct orientation.



## CAUTION: Be sure to read, follow and understand the following instructions.

Failure to follow this instruction manual may result in serious bodily harm to yourself or others.

Do Not Ride This Device. The M-145 Platform is not designed to carry passengers.

This device is a radio controlled, wireless device operating in the 2.4 GHz unlicensed frequency band. It is possible that interference from an outside source could cause unwanted movements of the unit. Ensure all users and bystanders are alert and clear of the unit.

This unit is not 100% waterproof. Driving this unit through puddles, lakes, streams, rivers, snow, ice, sleet or rain could damage the unit.

The M-145 platform moves fast and is heavy. Slamming the bumpers into people or stationary objects can cause substantial damage to the unit, the object, or bodily harm to the person. Avoid this at all times.

This unit is not a tow truck or plow. Using this unit to pull or push heavy objects is not recommended. It could cause severe damage to the unit.

Continuing to apply power to the unit when stuck (when at least one wheel on each side is not turning) will likely damage the electronics. This stall condition will cause the motors and motor controller to overheat and could cause permanent damage.

Turn the power OFF when not in use.

Do not drive the unit off jumps and ramps. Do not drop the unit. Do not jump onto the M-145. Any of these actions could cause the chassis to bend or may cause damage to the motors and motor shafts.

He Ideal Portable Battery Charger

The Ideal Portable Battery Charger

S PEAR LIMITED WARRANTY

WithCo Engineering, Inc. will enginee or repair, at its option, this product or any product component found to have defeative materials or workmanshy within two years of the original states recipt, which is required as proof of purchase to the original states recipt, which is required as proof of purchase to not the original states recipt, which is required as proof of purchase to not the original states recipt, which is required as proof of purchase to not the original states recipt, which is required as proof of purchase to not the original states recipt, which is required as proof of purchase to not the original states recipt, which is required as proof of purchase to office the original states recipt, which is required as proof of purchase to the date of this warranty.

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\*\*Any implied warranty, so the immitted to the terms and duration of the warranties expressly provided by this limited warranty. Some states/provinces to not allow limitations on the duration of the problem. Includes a copy of the original state recept. Carefully pedage the product and send fromes for a specific purpose, shall be immitted to the terms and duration of the problem. Include a copy of the original state recept. Carefully pedage the product and send from spiral states recept. Carefully pedage the product and send they almost, smalled with the product stating your name, adverse, telephone number and description of the problem. Include a copy of the original state recept. Carefully pedage the product and send many states and send the problem. Include a copy of the original state recept. Carefully pedage the product and send many states and send the product. The copy is product to the place you purchased it, you can produce the limited to the product states provided by the pr



# $\mathsf{BATTERY}$ $\mathsf{DOC}_{\!\scriptscriptstyle{n}}$

# The Ideal Portable Wallmount Battery Charger

peak condition 24hours a day 365 days a year. charger that will safely charge and maintain your battery at electronics perfect for lead acid/gel 12-Volt batteries. The Available in 1Amp and 2Amp versions, this range **BATTERY DOC**<sub>®</sub> is a highly efficient, reliable battery Wallmount Battery Chargers employs state of the art

## **FEATURES**

- Small Lightweight construction.
- UL 1236 approved for everyday use
- Short Circuit protected with Automatic Recovery.
- Three Color LED Charge Indicator
- Electronically monitored Over Current Limiting
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- Battery Clips and terminals for easy connection
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Additional accessories available. Contact WirthCo Engineering, Inc. for more information

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- SAVE THESE INSTRUCTIONS

  This manual contains important safety and operating instructions for battery charger model numbers #20030 & #20033 \*\*

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- Connect and disconnect discuppt clips only after setting any charger switches to off position and removing as α from electric outlet. Never allow clips to touch each other.
   b. Attach olips to battery and chassis as indicated in 13(e), 13(f), 14(b), & 14(d).
- 13. FOLLOW THESE STEPS WHEN BATTERY IS INSTALLED IN VEHICLE, A SPARK NEAR BATTERY MAY CAUSE BATTER EXPLOSION. TO REDUCE RISK OF A SPARK NEAR BATTERY:
- a. Position ac and dc cords to reduce risk of damage by hood, door, or moving engine part.
   b. Stay clear of fan blades, belts, pulleys, and other parts that can cause injury to persons.
   c. Check polarity of battery posts. POSITIVE (POS, P, +) battery post usually has larger diameter than NEGATIVE (NEG, N,-) post.
- d. Determine which post of battery is grounded (connected) to the chassis. If negative post is grounded to chassis (a in most vehicles), see (e). If positive post is grounded to the chassis, see (f), e. For negative-grounded vehicle, connect POSITIVE (REDs) (ip from battery charger to POSITIVE (POS. P, +) ungrounded post of battery. Connect NEGATIVE (BLQKT) dip to vehicle chassis or engine block away from battery Do not dip to carburetor; fuel lines, or sheet-metal body parts. Connect to a heavy gage metal part of the frame o
- engine block.

  f. For positive-grounded vehicle, connect NEGATIVE (BLACK) dip from battery charger to NEGATIVE (NEG, N, -) unigrounded past of battery, connect POSITIVE (RED) dip to vehicle chassis or engine block away from battery, not connect clip to carburator, fuel lines, or sheet-metal body parts. Connect to a heavy gage metal part of the
- h. See operating instructions for length of charge information. frame or engine block.

  9. When disconnecting charger, turn switches to off, disconnect AC cord, remove clip from vehicle chassis, and then remove clip from battery terminal.

# 14 FOLLOW THESE STEPS WHEN BATTERY IS OUTSIDE VEHICLE. A SPARK NEAR THE BATTERY MAY CAUSE BATTERY EXPLOSION. TO REDUCE RISK OF A SPARK NEAR BATTERY: Check polarity of battery posts. POSITIVE (POS. P. +) battery post usually has a larger diameter than NEGATIVE (NEG, N. -) post. connect Language of the post of the post. Connect POSITIVE (RED); charger dip to POSITIVE (POS. P. +) post of battery. Position yourself and free end of cable as far away from battery as possible – then connect NEGATIVE (BLACK)

- charger clip to free end of cable.

  Do not face battery when making final connection.

  When disconnecting charger, always do so in reverse sequence of connecting procedure and break first connection while as far away from battery as practical, marine (load) battery must be removed and charged on shore. To charge it on board requires equipment specially designed for marine use.

# OPERATING INSTRUCTIONS Part No. 20030 & 20033

ψ	Check for incorrect battery	Vbatt > 13.5Volts	Green (blinking)
	(OR not connected)		
	Battery fully charged	Vbatt 13.5Volts	Green
	Charging < 70% full Amps	Vbatt 13.0 -13.5Volts	Yellow
	Charging full Amps (1 or 2A)	Vbatt 7-13Volts typ.	Red
1 & 2	Charging	Vbatt 3-7Volts typ.	Red (blinking)
2	Battery Voltage below 3Volts	No Output	Off
	Output Shorted	No Output	Off
	Charger not plugged in	No Output	Off
*NOTES	CONDITION	OUTPUT VOLTAGE	LED STATUS

## \*NOTES:

- Vbatt is the battery voltage
   Battery overly discharged; may not fully charge.
   LED may blink momentarily if the above connection procedure is not followed.